

# Gravitational waves from precessing binaries

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Caltech/JPL seminar

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# Outline

Subtitle: Planned search of LIGO data  
(some tricks relevant to LISA)

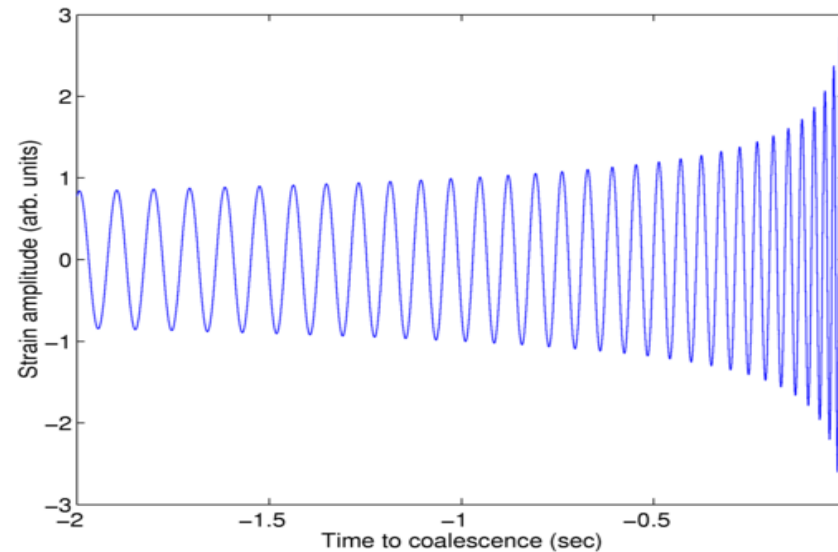
1. Context and motivation
2. Basic binary search (NS/NS)
3. Complications for BH/BH binaries
4. Complications for precessing binaries (mainly BH/NS)

## Inspiring compact binaries

Two objects orbit each other

Compact objects  $\Rightarrow$  close orbit  $\Rightarrow$  high velocity

Emission of gravitational waves shrinks orbit

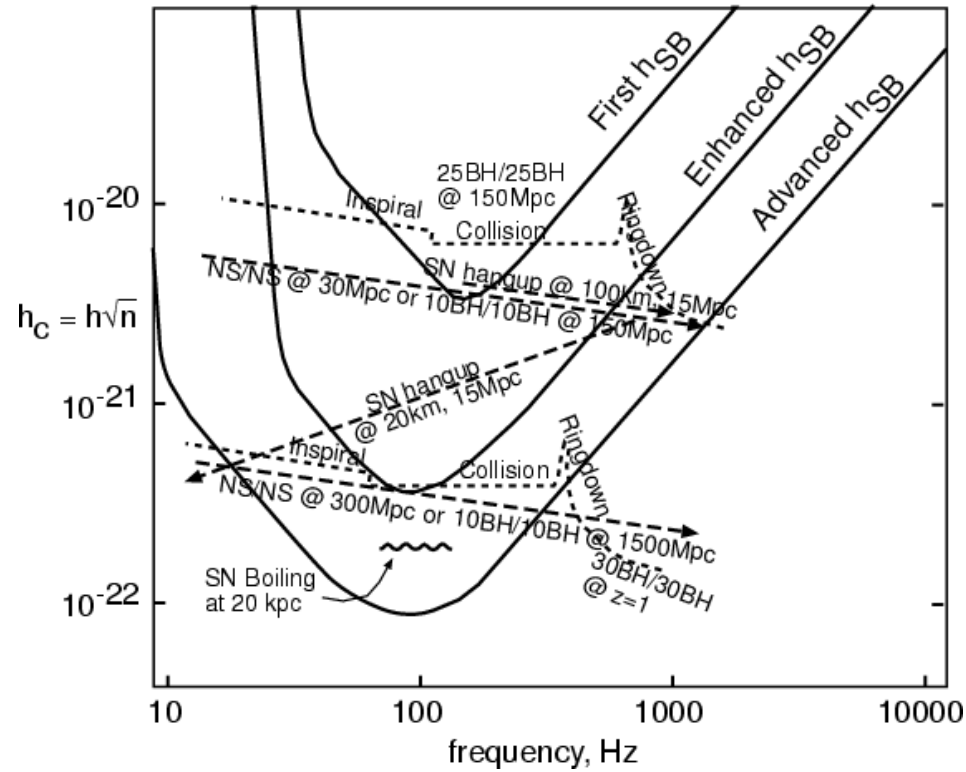


$$h \propto \frac{M^{5/3} f^{2/3}}{D} \cos \psi$$

$$\tilde{h} \propto f^{-7/6} e^{i\psi(f)}$$

# LIGO sources

(graph from Thorne)



Boundary between inspiral and plunge/collision scales as  $1/\text{mass}$ .

## Why binaries are important

Known to exist: PSR B1913+16 (Hulse & Taylor ApJL 1974)

Event rate predictions for initial LIGO (Kalogera's group):

- NS/NS up to 1/few yr at range 20 Mpc based on observations of PSR J0737-3039
- BH/NS and BH/BH up to 1/few yr at range 40 Mpc and 100 Mpc based on stellar evolution codes

Best modeled source: post-Newtonian approximation carried to  $O(v/c)^7$  (cf. perturbative QED).

Good modeling lets you use matched filtering, which is the best technique for detecting faint signals in noise.

## Three kinds of binaries - 1

NS/NS:

- “Solid” event rates based on observations
- Masses  $1-3 M_{\odot}$  each ( $1.4 M_{\odot}$  observed)
- Plunge  $\simeq 1400$  Hz  $\Rightarrow$  post-Newtonian at 150 Hz
- Spins, quadrupoles, etc don't matter at 150 Hz

Upper limit searches have been done:

- Algorithms stable, developed during 1990s
- Caltech 40m (Allen et al. PRL 1999)
- TAMA (Tagoshi et al. PRD 2001)
- LIGO S1 w/GEO (Abbott et al. PRD 2004)

## Matched filtering - basic

Define inner product between functions  $a$  and  $b$  as

$$\langle a, b \rangle = 4\text{Re} \int_0^\infty df \frac{\tilde{a}^*(f)\tilde{b}(f)}{S_h(f)},$$

where  $S_h$  is the power spectral density of strain noise.

Signal-to-noise ratio for linear filter is defined by

$$\rho^2 = \langle h, u \rangle^2 / \langle u, u \rangle,$$

where  $h$  is strain data and  $u$  is template (predicted waveform).

Optimal filter (highest  $\rho^2$ ) is then  $u \propto h$ ; set  $\langle u, u \rangle = 1$  since amplitude drops out.

Sinusoidal signals: Filtering amplifies  $\rho^2$  by number of cycles, more sensitive to phase than amplitude (mostly).

## Matched filtering - nuisance parameters

Sinusoidal signal w/unknown time & phase shifts  $t_0$  &  $\delta$ :

$$h(t) \propto \cos[\psi(t - t_0) + \delta]$$

Maximize over all values of shifts (“nuisance parameters”).

Maximize over  $\delta$  by redefining signal-to-noise ratio functional

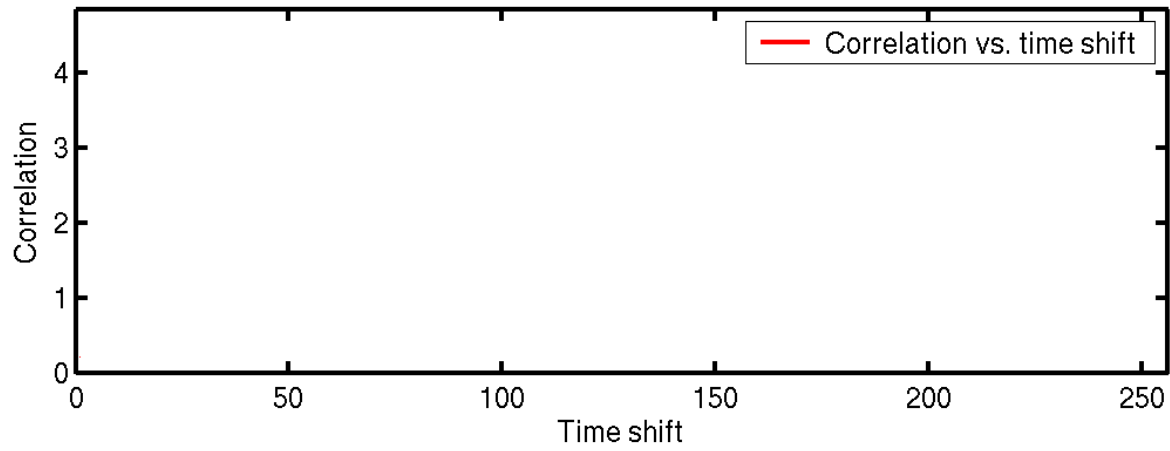
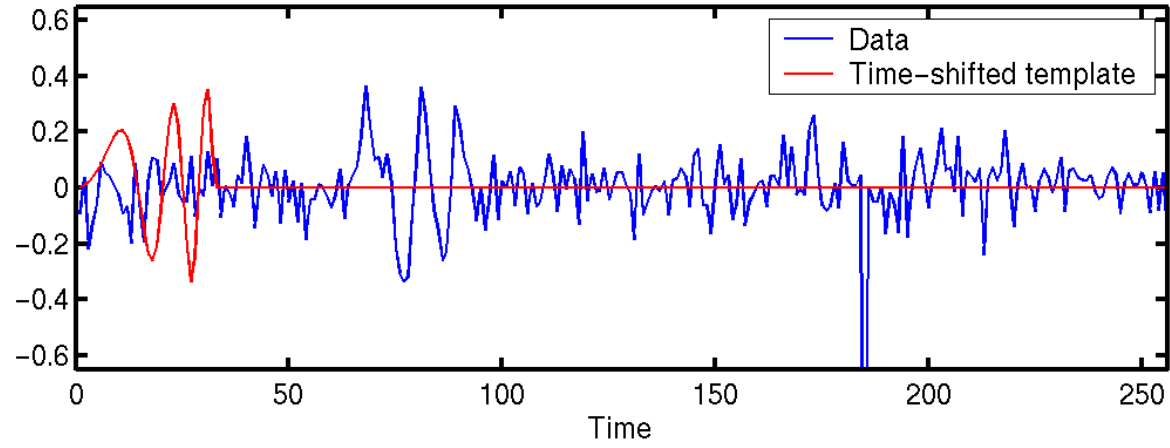
$$\rho^2[h] = \langle h, u \rangle^2 + \langle h, v \rangle^2, \quad u \propto \cos \psi, \quad v \propto \sin \psi.$$

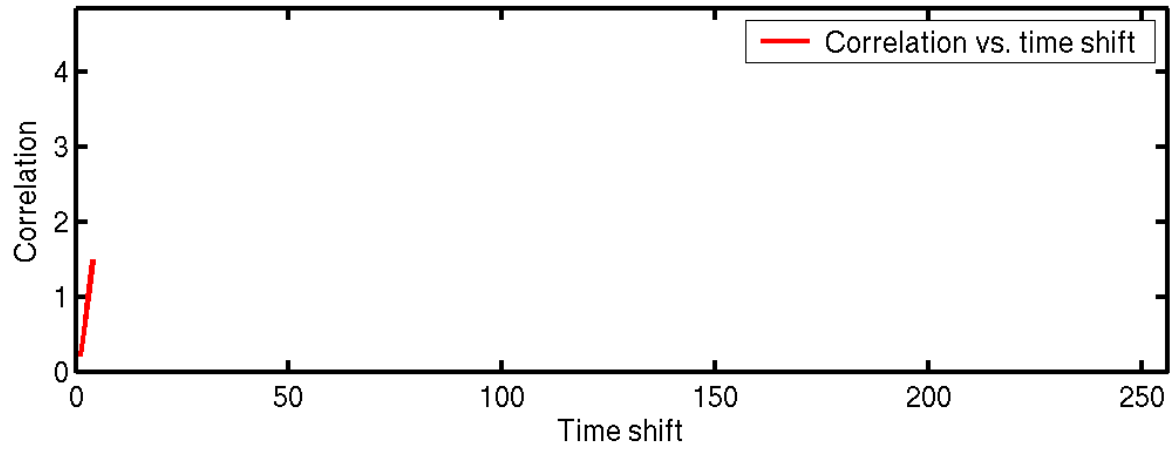
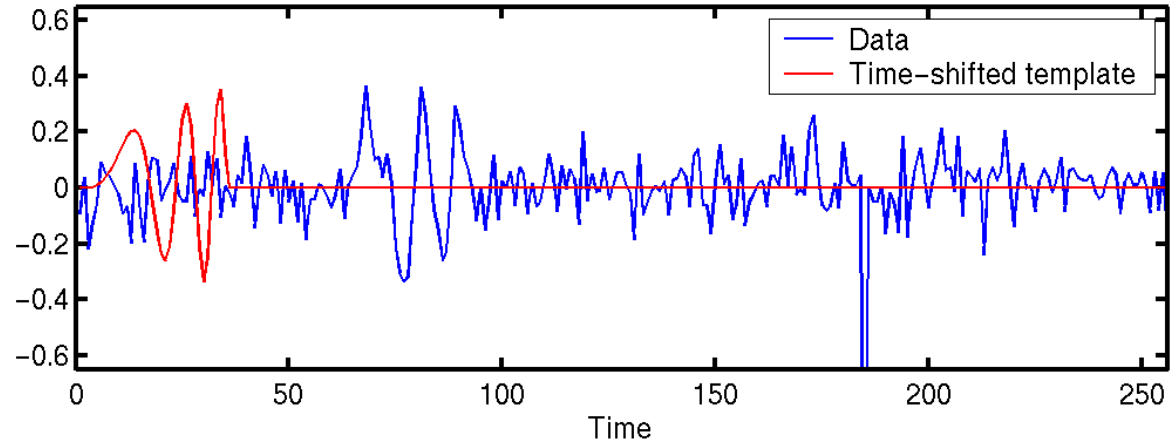
Adds power in sine and cosine filters;

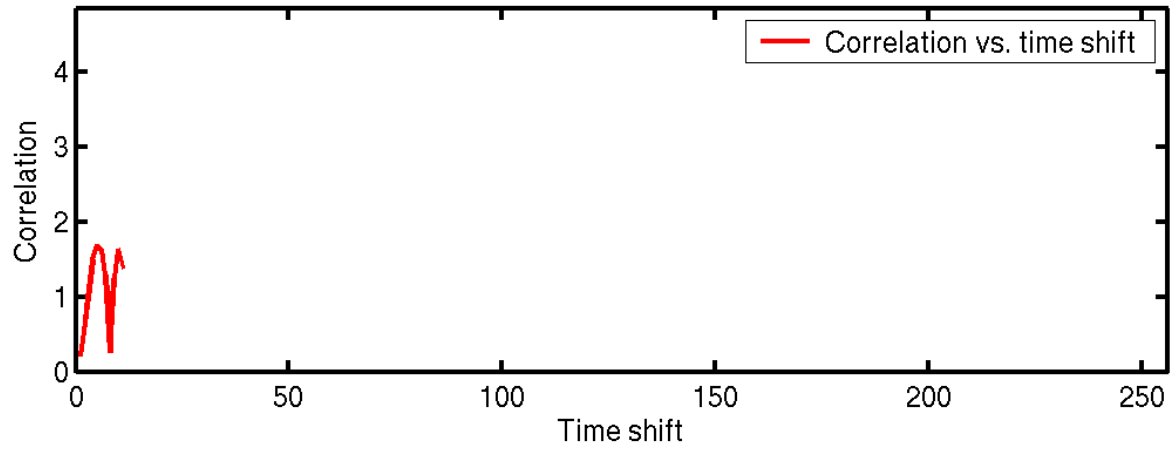
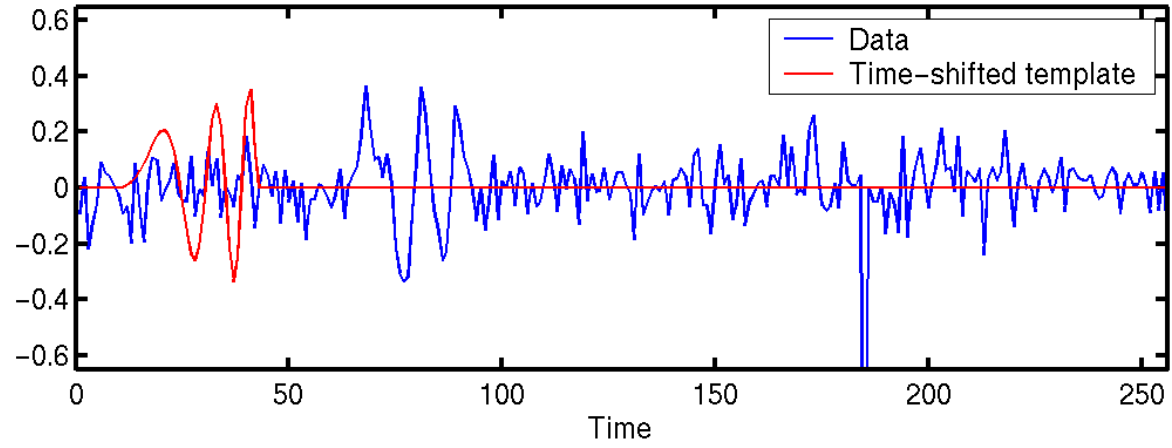
Requires  $(u, v) = 0$  to avoid double-counting.

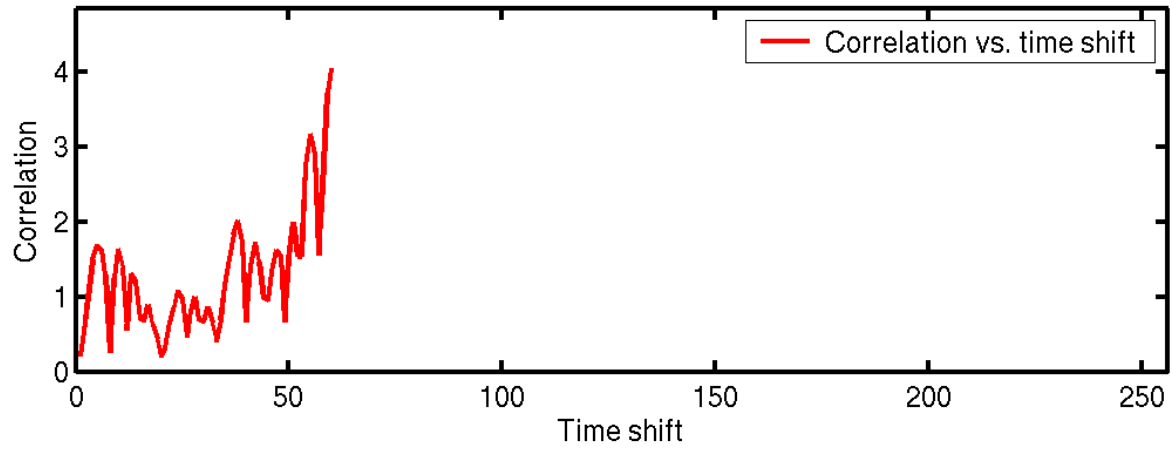
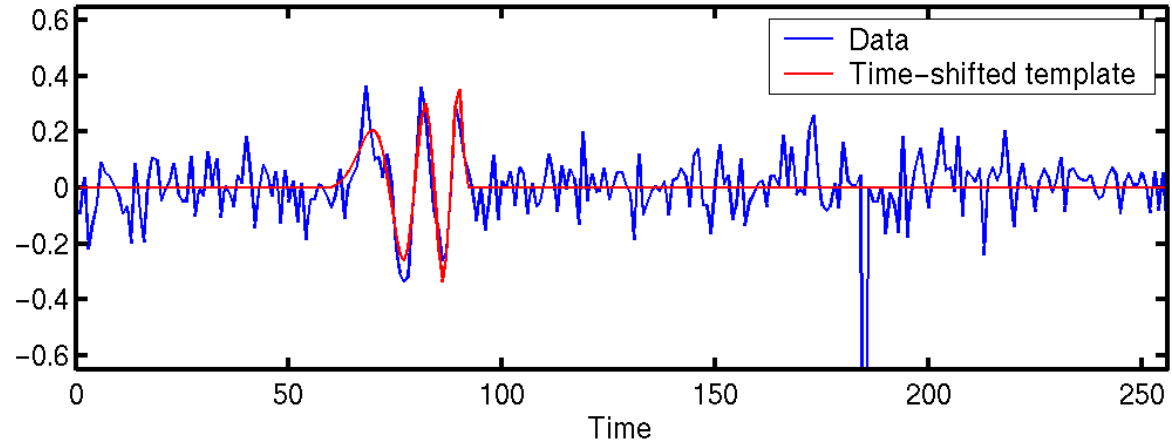
Maximize over  $t_0$  by hunting for peaks in Fast Fourier Transform.

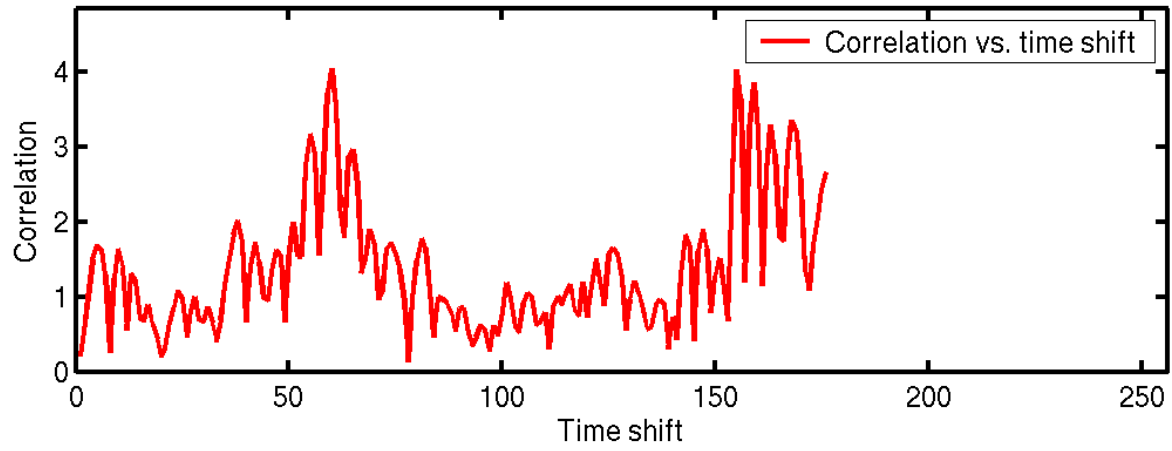
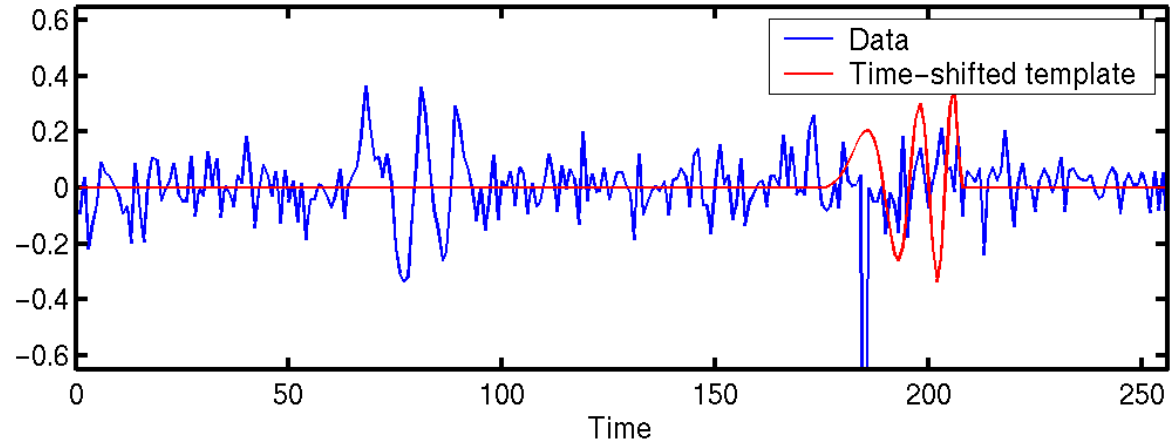
(graphics by Peter Shawhan)

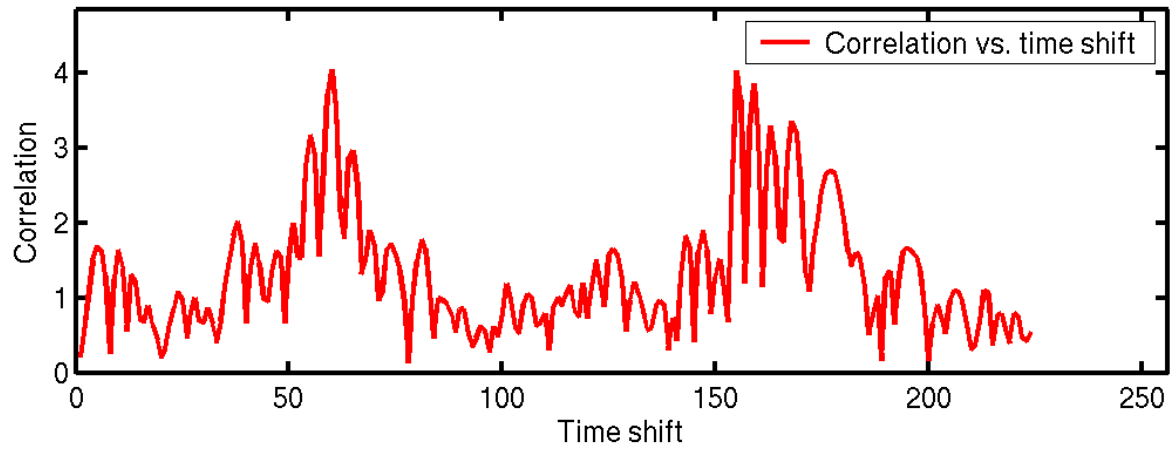
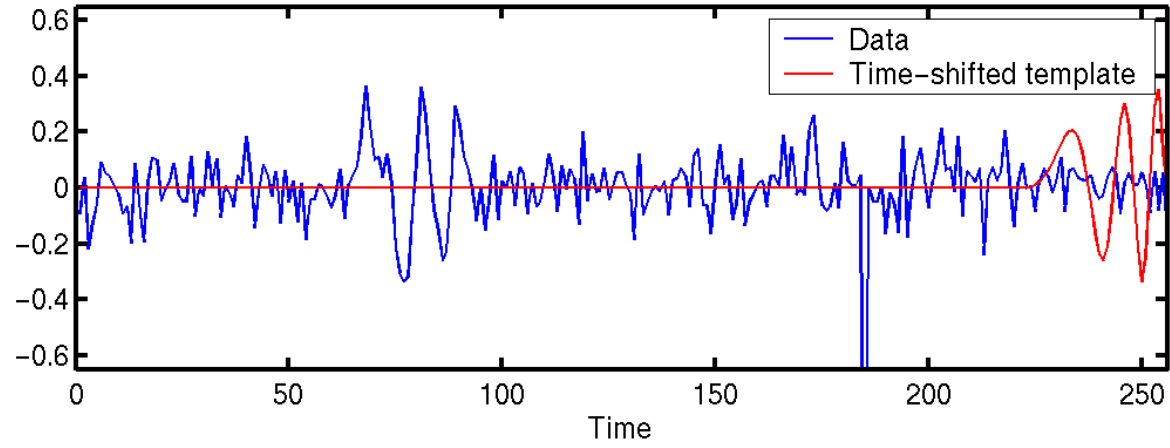












## Matched filtering - shape parameters

Templates form manifold with shape parameters  $\vec{\lambda}$  as coordinates. Not covered by a few orthogonal functions: what to do?

How much  $\rho$  do we lose filtering a signal  $u(\vec{\mu})$  with a nearby template  $u(\vec{\lambda})$ ? Falls off quadratically in  $\vec{\lambda} - \vec{\mu}$ .

Define metric so that (Owen PRD 1996)

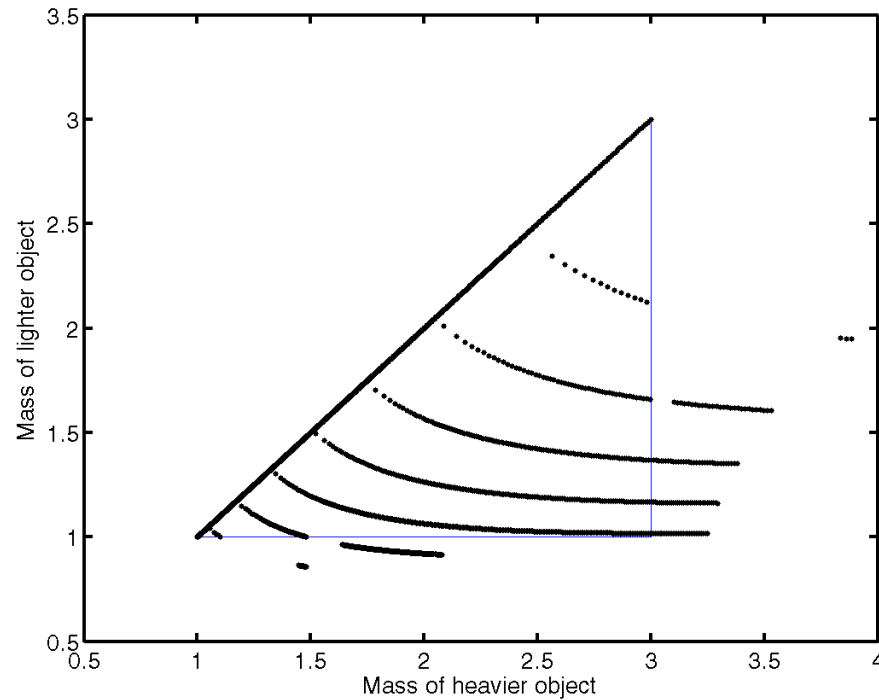
(proper distance)<sup>2</sup> = fractional loss in  $\rho$ :

$$g_{ab} = -\frac{1}{2} \frac{\partial}{\partial \lambda^a} \frac{\partial}{\partial \lambda^b} \langle u(\vec{\mu}), u(\vec{\lambda}) \rangle |_{\lambda=\mu}$$

(or equivalently by projecting from information matrix).

Post-Newtonian template metric can be written in terms of a dozen integrals of the form  $I_p = \int_0^\infty df / f^{p/3} / S_h(f)$ .

## NS/NS parameter space



Lay grid with constant *proper* spacing  $ds^2 = \mu$  (mismatch);  
Number of templates = proper volume / volume per template.

## Signal-based vetoes

Signal-to-noise isn't everything: high  $\rho^2$  from kicking a test mass.  
Why?  $\langle a, u \rangle$  can be large even if  $\langle a, u \rangle / \sqrt{\langle a, a \rangle} \ll 1$ .

Get rid of transients with  $\chi^2$  veto: (Allen et al. PRL 1999)

Divide spectrum into  $p$  bands of equal power if signal is present;

Test if observed power  $\rho_i$  really is distributed equally:

$$\chi^2 = p \sum_{i=1}^p [\rho_i - \rho/p]^2$$

Veto something with large  $\rho^2$  if it's also got large  $\chi^2$ .

## Three kinds of binaries - 2

BH/BH (w/o precession):

- Can neglect spins if small or parallel to orbit
- Event rates less certain, but signals are stronger
- Masses  $3\text{--}25 M_{\odot}$  each (not MACHOs)
- Plunge  $\simeq 150 \text{ Hz}$   $\Rightarrow$  too relativistic for post-Newtonian

Search strategies being implemented:

- Use Caltech *ad hoc* waveforms
- Complications due to mismatched filtering
- Algorithms still not fully worked out
- Implement them anyway on S2 & S3 data!

## BH/BH waveforms

Late inspiral/early plunge: Post-Newtonian gradually going bad, waveforms still too long for numerical relativity (10s of cycles). Different versions of post-Newtonian expansion diverge in different ways at end.

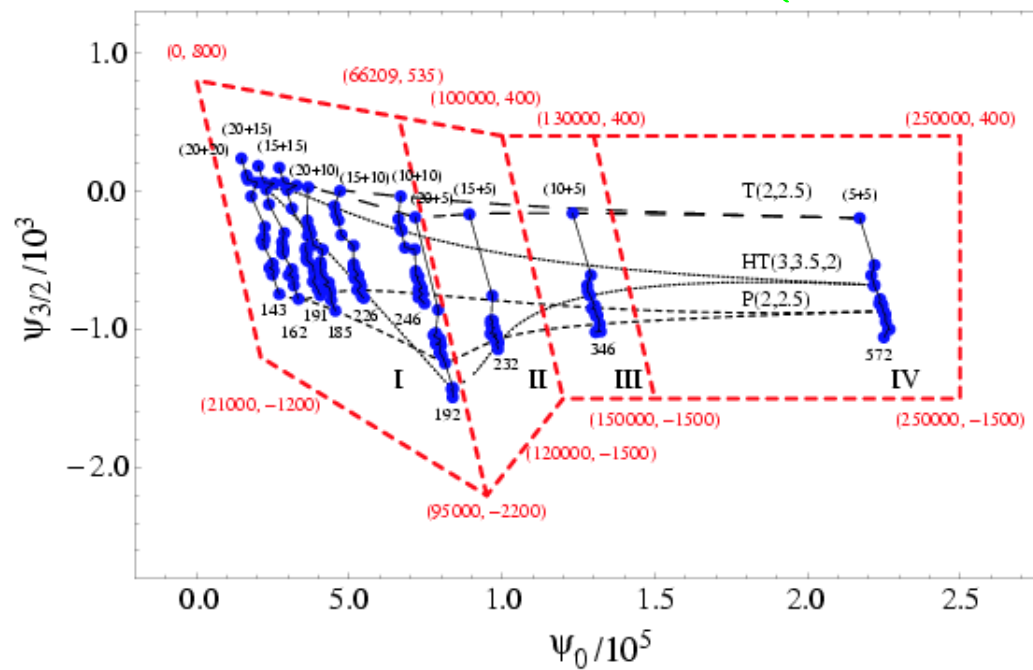
Solution: Buonanno, Chen, and Vallisneri PRD 2003

$$\tilde{h}(f) = \tilde{h}_{\text{old}}(f) \times (1 - \alpha f^{2/3}) \times \Theta(f - f_{\text{cut}})$$

Fits all versions of late inspiral (< 10% loss due to systematics);  
Requires two new shape parameters (not too many templates).

# BH/BH search

Parameter mapping becomes uncertain: (BCV 2003)



Search under development at Cardiff.

## Three kinds of binaries - 3

Precessing BH/BH or BH/NS:

- No direct observations, but range is high
- Many BH spins misaligned w/orbit  $\Rightarrow$  precession
- Modulates waveforms, esp. at “extreme” mass ratios
- Plunge 150 Hz (BH/BH) to 900 Hz (BH/NS)
- Post-Newtonian still OK for BH/NS, *ad hoc* for BH/BH

Data analysis was thought hopeless:

- Carries more information, but makes detection harder
- Clever mathematical handling of modulation
- Computationally feasible, though expensive

## Three regimes of precession

Very complicated dynamics (Apostolatos et al. PRD 1994)  
Not generally closed-form expressions for waveforms.

$L \gg S$ : little modulation

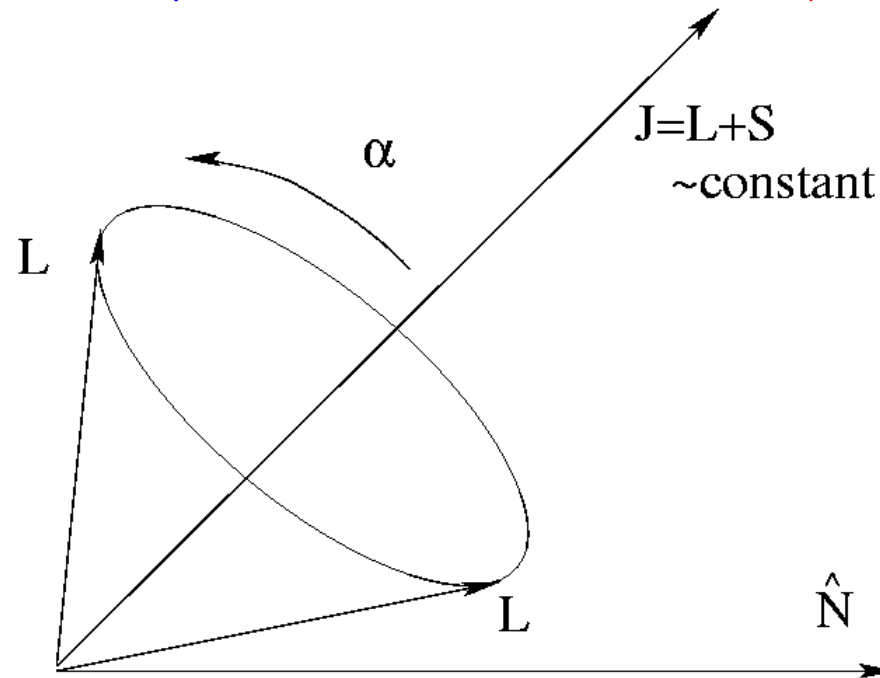
$L \simeq S$ : possible “transitional precession” (chaos?)

$L \ll S$ : strong modulation

Several more parameters (9 total), was thought to be hopeless search (Apostolatos PRD 1996).

## Why $L \ll S$ is important

Detector response depends on  $\hat{L} \cdot \hat{N} = \hat{J} \cdot \hat{N} + \text{const.} \times \cos \alpha$ ,



which varies most for  $L \ll S \Rightarrow m_2 \ll m_1$ .

So focus on BH/NS binaries (also nice parameter mapping).

## Detector response

$$h = F_+ A_+ \cos \psi + F_\times A_\times \sin \psi = A \cos(\psi + \delta),$$

$$A = \sqrt{(F_+ A_+)^2 + (F_\times A_\times)^2},$$

$$\delta = \tan^{-1}[F_\times A_\times / (F_+ A_+)],$$

where  $F_+, F_\times$  depend on sky position and  $A_+, A_\times$  on source.

For binaries:  $A_+ = 1 + (\hat{L} \cdot \hat{N})^2$ ,  $A_\times = 2\hat{L} \cdot \hat{N}$

Precession changes  $\hat{L} \cdot \hat{N}$ , modulates at angular frequency  $d\alpha/dt$ .

For pulsars  $F_+, F_\times$  change and  $A_+, A_\times$  are fixed; but same type of modulation.

For freely precessing pulsars or precessing binaries with LISA, all four quantities change; but same problem again.

## The $\mathcal{F}$ -statistic

Developed for pulsars:  $A$ 's fixed,  $F$ 's change

(Jaranowski, Krolak & Schutz PRD 1998)

Applied to precessing binaries:  $A$ 's change,  $F$ 's fixed

(Buonanno, Chen, & Vallisneri PRD 2003)

Full power of matched filtering by including amp. modulation;

Maximizes quickly over extra nuisance parameters (angles);

Must mean something physically?

## How the F-statistic works

Complex modulation in frequency domain:

$$\tilde{h}(f) \propto [Z_0 + Z_1 \cos \alpha(f) + Z_2 \sin \alpha(f)] f^{-7/6} e^{i\psi(f)}$$

Carrier  $e^{i\psi}$  gains sidebands  $e^{i(\psi \pm \alpha)}$ .

Spacing between carrier & sidebands is given by  $\alpha$ .

Relative amplitudes depend on  $\hat{J} \cdot \hat{N}$  and  $\alpha$ .

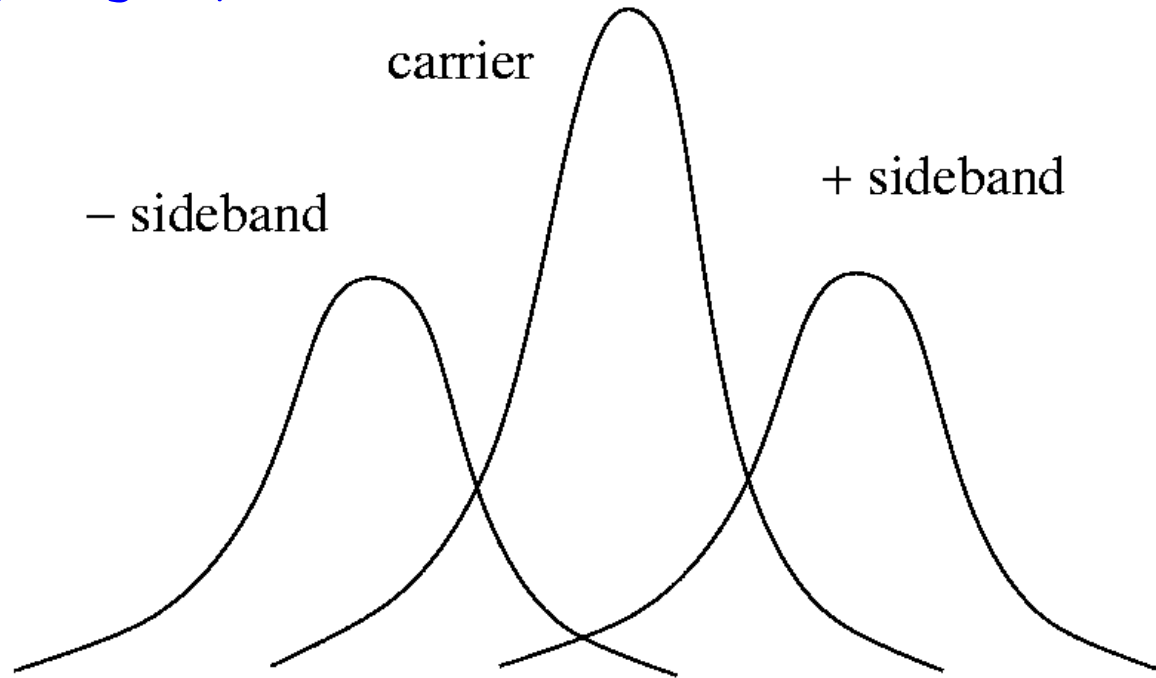
For strong modulation, carrier & sidebands are orthogonal:

$$\rho^2 = \mathcal{F} = \langle h, \cos \psi \rangle^2 + \langle h, \cos(\psi + \alpha) \rangle^2 + \langle h, \cos(\psi - \alpha) \rangle^2 \\ + \text{sine filters}^2$$

adds power in carrier & sidebands, sine & cosine of each.

## Carrier and sidebands

If they're not orthogonal, make them so with Gram-Schmidt.  
But then you get problems... [Pan et al. 2004](#)



## Parameter-space metric

Strong modulation makes metric simple: (Owen & Vecchio 2004)

$$2g_{ab} = 3(\partial_a\psi, \partial_b\psi) + 2(\partial_a\alpha, \partial_b\alpha) - \text{projections}$$

Block diagonal, two mass parameters  $(\psi_0, \psi_3)$  and one spin parameter  $\beta : \alpha = \beta f^{-2/3}$  (good for  $m_1 \gg m_2$ ).

Not-so-strong modulation:

Still pretty simple, only need sine & cosine moment functions

$$S_p(\beta) = \int \frac{df \sin(\beta f^{-2/3})}{f^{p/3} S_h(f)}, \quad C_p(\beta) = \int \frac{df \cos(\beta f^{-2/3})}{f^{p/3} S_h(f)}$$

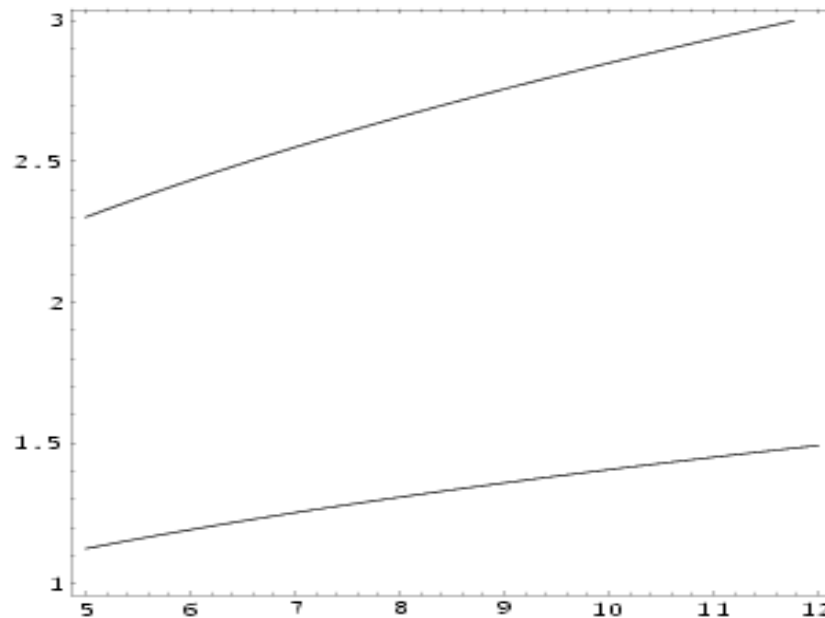
These can be stored in an interpolation table (up to  $2\beta_{\max}$ ).

Infinitesimal modulation:

Singular metric (physics is breaking down) so forget it.

## Which systems have strong modulation?

Or “where is  $\langle \text{carrier, sideband} \rangle < 0.1$  in  $m_{\text{NS}}-m_{\text{BH}}$  plane?”

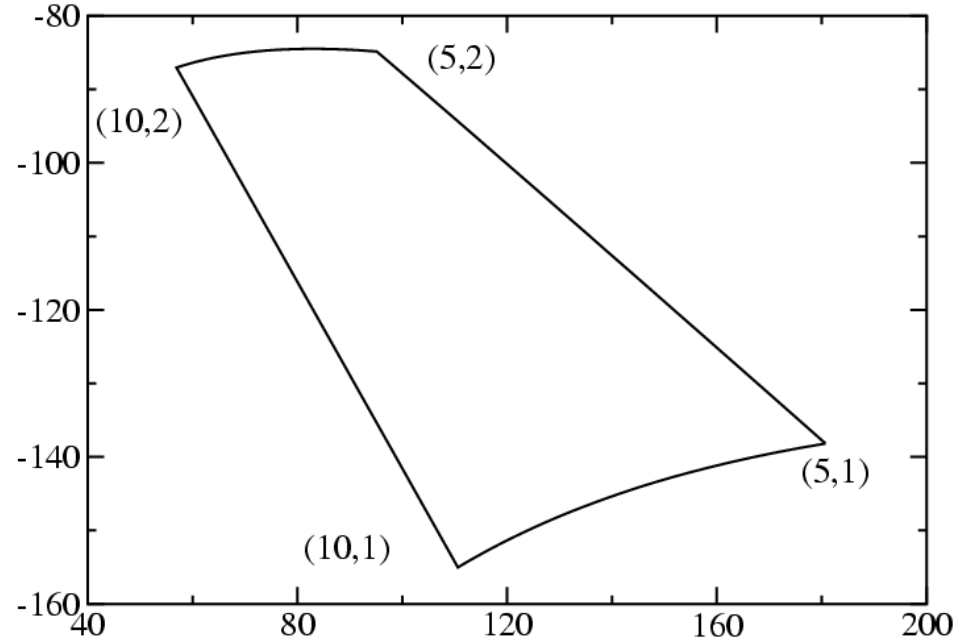


Below top line: Strong for  $S_1/m_1^2 = 1$  (GR maximum).

Below bottom line: Strong for  $S_1/m_1^2 = 0.5$  (believable).

## 2D space: mass parameters

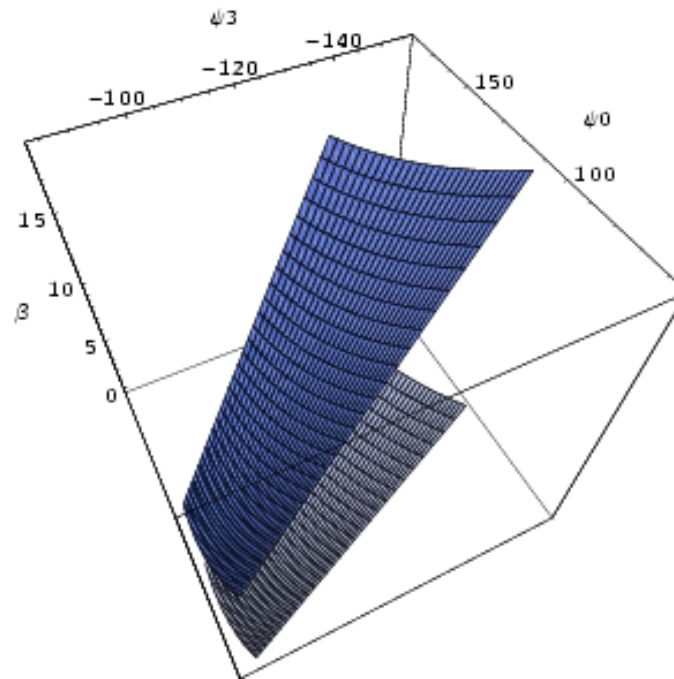
Astrophysical parameter range:  $m_1 \in (5, 10)M_\odot; m_2 \in (1, 2)M_\odot$



Rectangle in  $m_1 m_2$  plane  $\rightarrow$  wedge in  $\psi_0 \psi_3$  plane.

## 3D space: Masses and spin

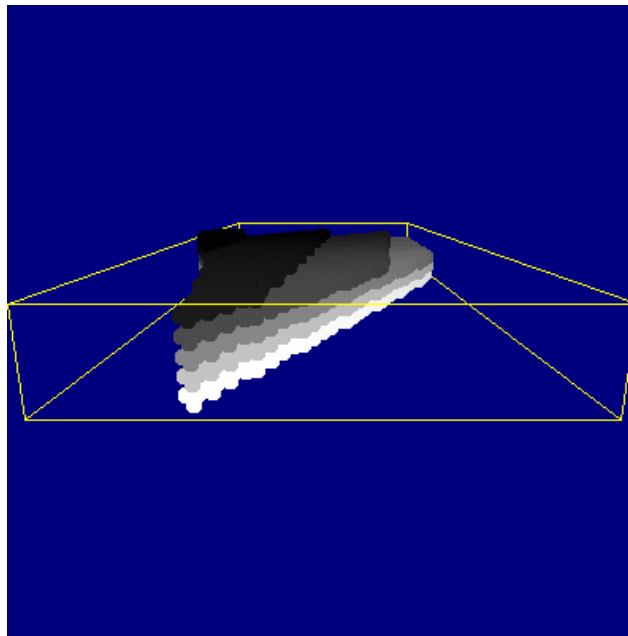
Only large body's spin matters:  $S_1/m_1^2 \in (0, 1)$



Strongest modulation (highest  $\beta_{\max}$ ) is at extreme mass ratio.

## Template bank (LAL)

LIGO-I SRD noise, worst mismatch 100% ( $\mu = 1$ ) for legibility:



Template count is  $120\,000 (0.03/\mu)^{3/2}$ . (PRELIMINARY: wrong by factor 2?)

## Future issues

Too many templates for brute force search.

(in practice limited by computation of  $\chi^2$ , not  $\rho^2$ )

Better go hierarchical:

First pass scans data w/o sidebands, low  $\rho$  threshold.

Second pass includes sidebands on promising candidates from first pass w/higher threshold to weed out false alarms.

Need clever 3D tiling algorithms (basic one in place).

What will this do to  $\chi^2$  veto?